



SAFE URBAN AIR  
MOBILITY FOR EUROPEAN  
CITIZENS

# Project Overview

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## FINDINGS, RESULTS AND CHALLENGES

14/12/2022 Ghent - Belgium

**Elham Fakhraian, Ghent University**



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# AURORA consortium

## AURORA's Unmanned Aerial Vehicles

< 10 kg UAV



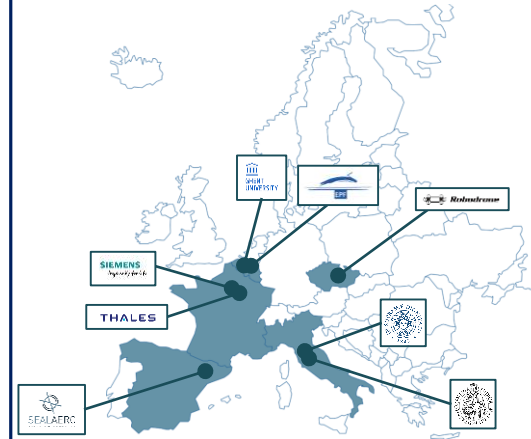
75 kg UAV



600 kg rotorcraft



8 partners in 5 EU states

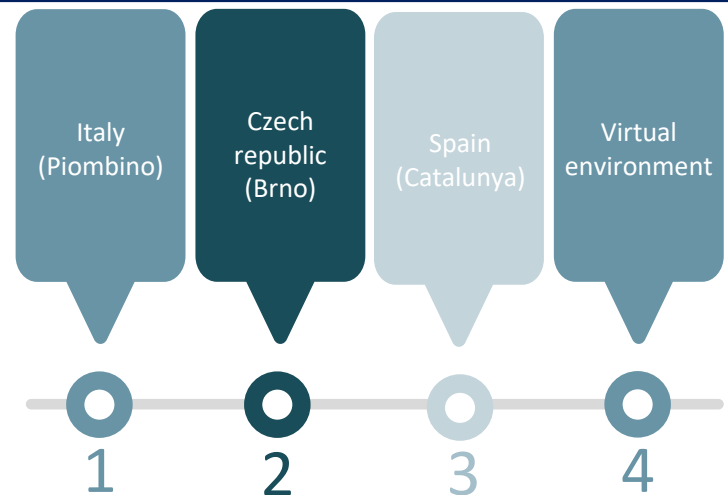


- SEAL Aero (coordinator)
- Ghent University
- European Passengers' Federation
- Thales
- University of Pisa
- University of Florence
- Robodrone
- Siemens

Starts  
DEC 01  
2020

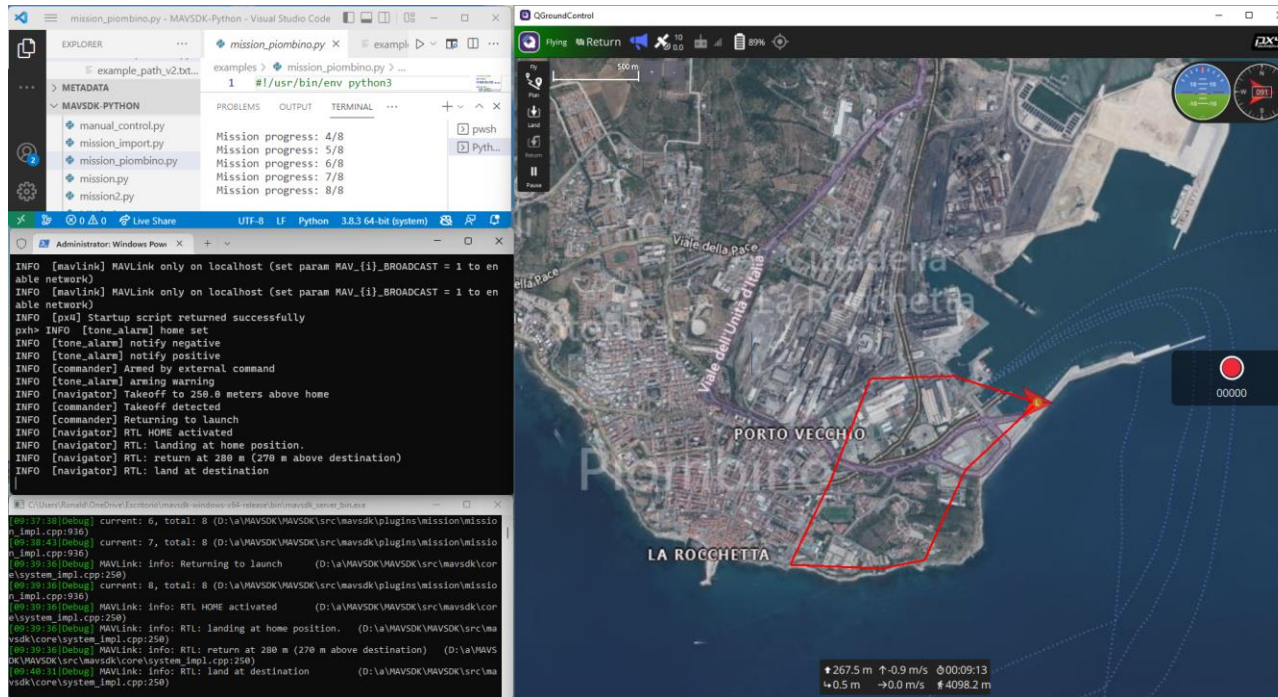
Ends  
NOV 30  
2023

Aurora demonstration and Potential locations





# Flight Simulation (Piombino – Italy)



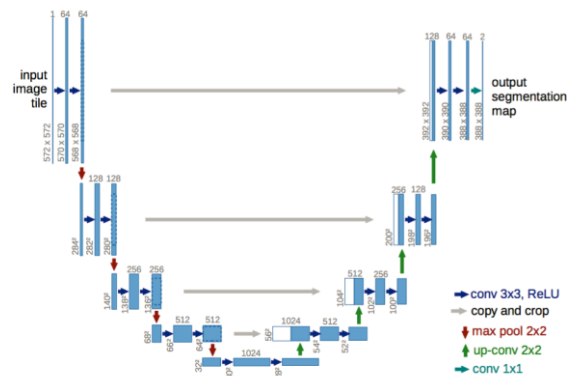
First integration of local path planner within the global path planner

Safe autonomous guidance-navigation solution for Dynamic global flight path planning and guidance

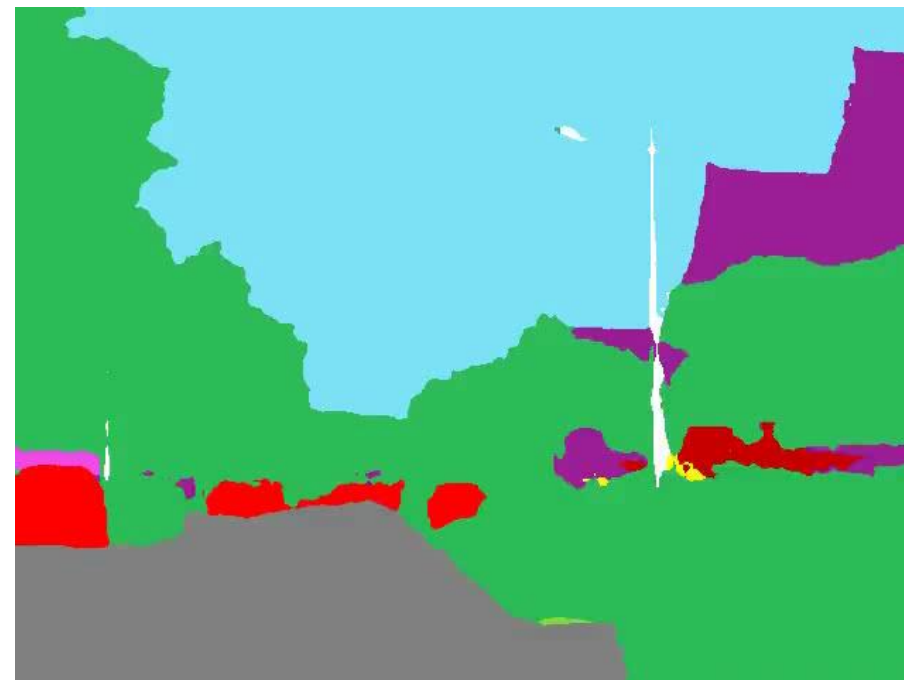
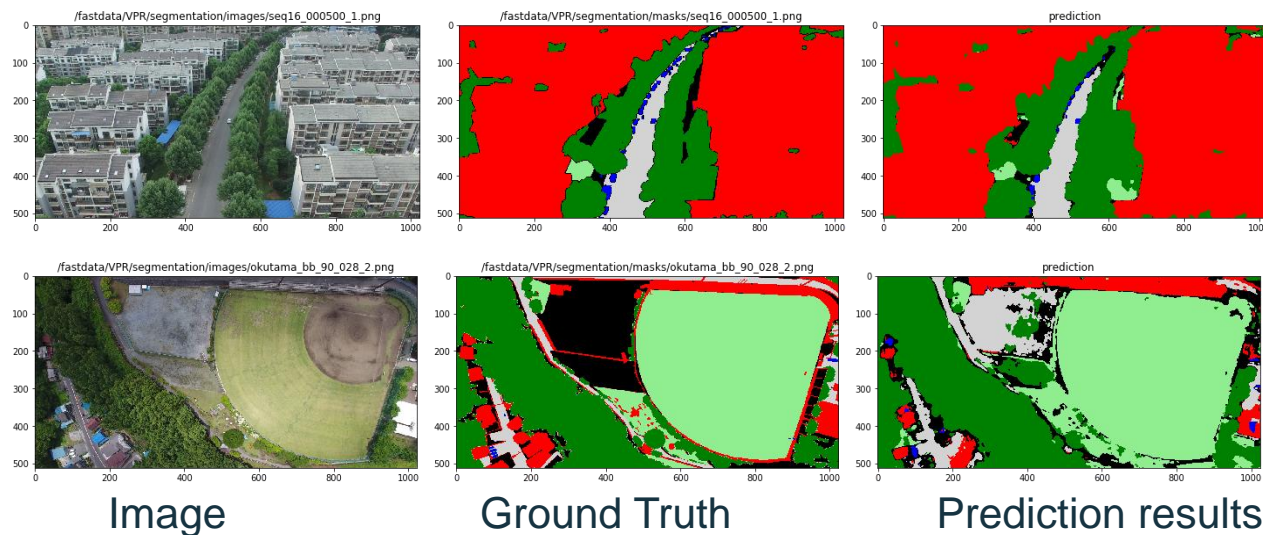
Exchanging information among Ground Control Station And Drone

# Safe landing site detection : Deep learning approach

## Architecture based on Encoder/Decoder

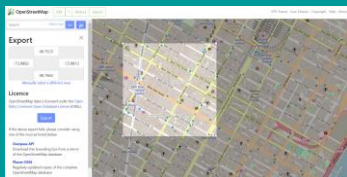


Building (red) , Road (gray), Static car (blue), Tree (dark green), Low vegetation (green), Background clutter (black)



# Safe autonomous guidance-navigation solution

Select part of a city in OSM



Use Blender for  
conversion

Use SUMO for  
conversion

3D  
buildings

Road  
network

Simcenter Prescan



3D environment generation

Simcenter Prescan

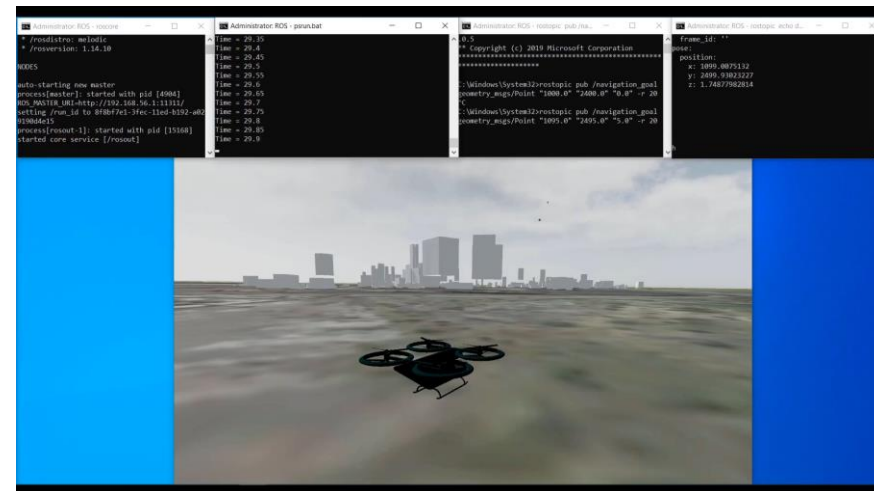


Image segmentation Sensor

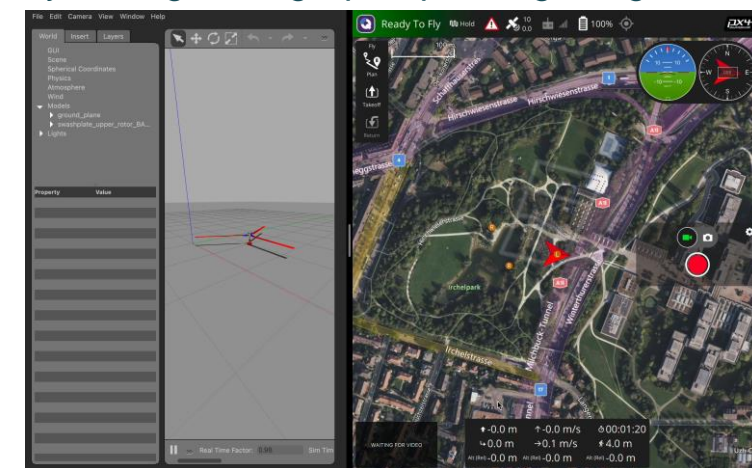
Simcenter Prescan



Synthetic environment  
generation for training of NN



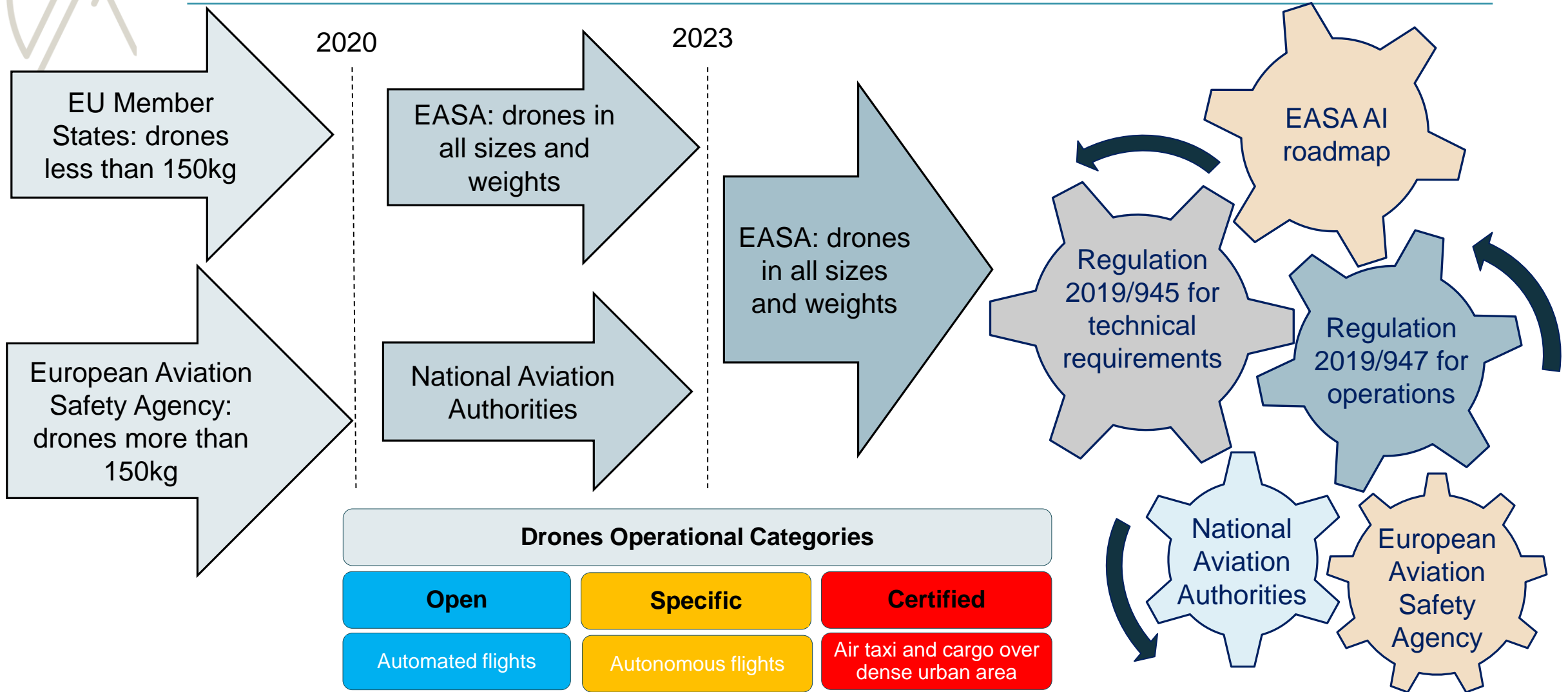
Dynamic global flight path planning and guidance



Autonomous Flight Control in Gazebo simulator



# European Union Drone Regulation



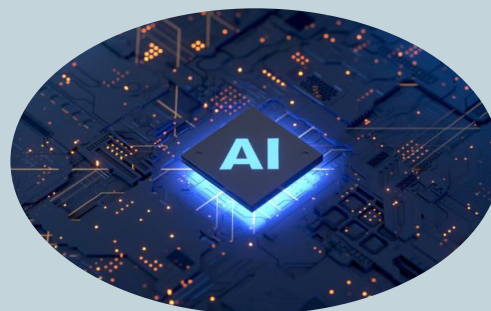
# A human-centric approach to AI in aviation

## Automatic UAV

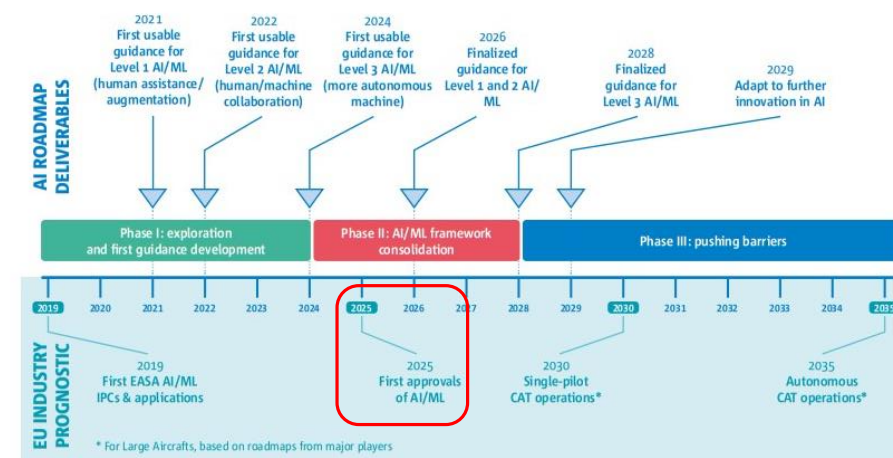
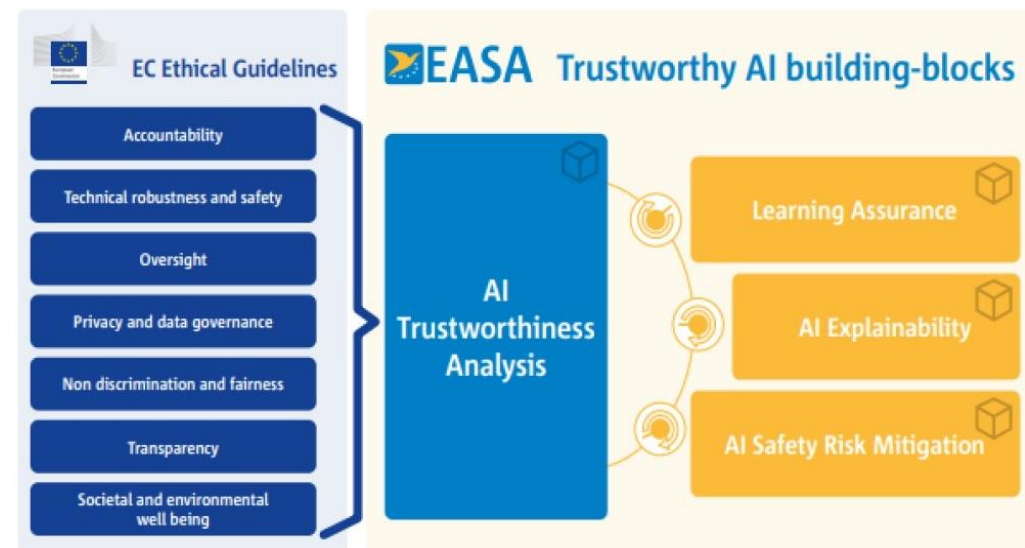


Automatic UAV flies on pre-determined routes, and the remote pilot intervenes in case of unforeseen events not programmed in pre-determined operation.

## Autonomous UAV



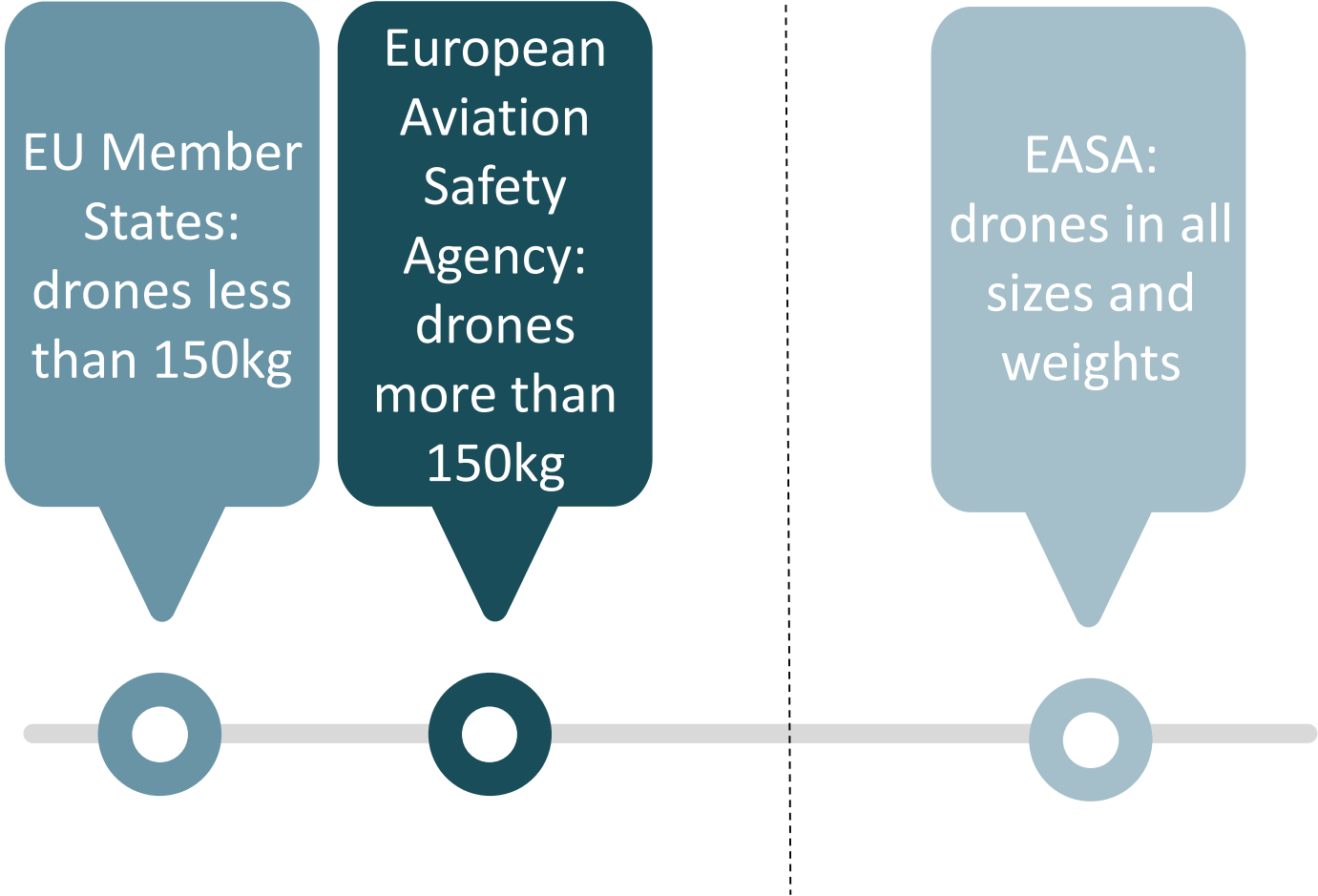
With the help of artificial intelligence, autonomous UAV must cope with unforeseen conditions and unpredictable emergencies to conduct a safe flight without the pilot's intervention.





# Conclusion

31 December 2020





# Thank you for your attention!

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<http://aurora-uam.eu/>